

JAKA Robotics Co., Ltd.

- 🙎 JAKA China: Building 33-36, No. 610 Jianchuan Rd, Minhang District, Shanghai, China
- A JAKA Germany: Siemensstr. 31, 90766 Fürth, Germany
- 👱 JAKA Japan: F Serebureito Aoi,1-6-14 Aoi, Higashi-ku,Nagoya-shi,Aichi-ken,Japan
- 👱 JAKA Malaysia: 5-G, Jalan Borealis 3, Bandar Cassia, 14110 Simpang Ampat, Penang, Malaysia

400-006-2665

Copyright © 2024 JAKA. All rights reserved.

Disclaimers:

The copyright belongs to JAKA and cannot be copied or reproduced in any form without written permission.

The company reserves the right to interpret and update the contents of the materials without notice.



PRODUCT SELECTION GUIDE

Global Leader in Flexible Intelligent Robotics



Product Matrix





No Teaching Pendant

Programming JAKA collaborative robots is made easy with our JAKA APP, available for Android and Windows devices. Traditional teaching pendants are no longer necessary.

Wireless Connection

Say goodbye to messy wires! JAKA cobots can now communicate and receive task assignments via their own WiFi connection, leaving you with a clean and safe workspace.

Safe Human-robot Collaboration

JAKA cobots are designed to work safely alongside humans, without the need for a safety fence, thanks to their collision detection module. Even the slightest bump can be detected, allowing the cobot to react and avoid causing harm.

Graphic Programming

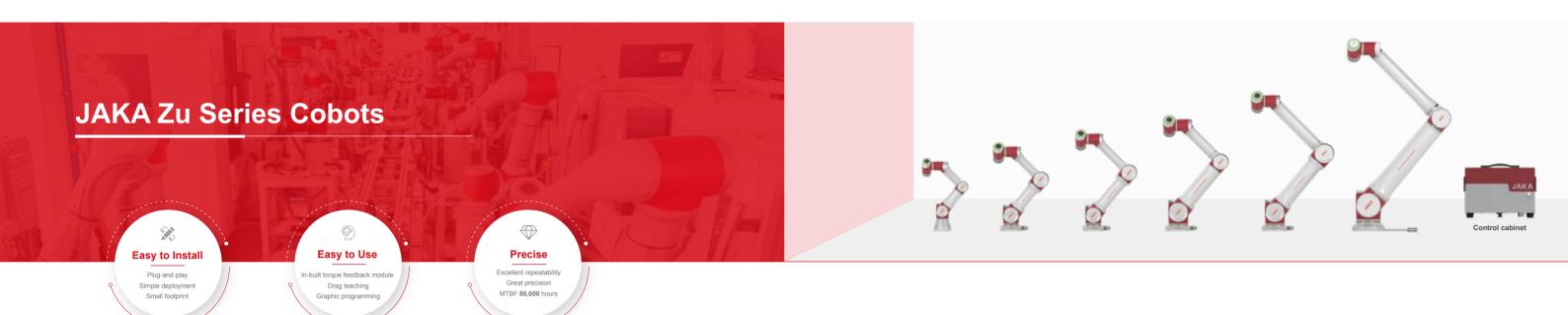
Our intuitive graphic programming software interface is designed for anyone to use, regardless of prior programming experience. Setting positions and tasks is a breeze with our user-friendly interface.

Drag Teaching

With our drag teaching function, users can deploy a cobot in just a few minutes. Simply move the cobot to any desired position, and it will instantly memorize it.

Plug-and-play

Install a JAKA cobot in just a few minutes, and mount it in any position or inclination. Our cobots are lightweight and are compatible with a wide range of grippers and end effectors. This makes them highly versatile and able to be deployed and re-deployed in any production environment.



	Parameter	JAKA Zu 3		JAKA Zu 5		JAKA Zu 7		JAKA Zu 12		JAKA Zu 18		JAKA Zu 20		
	Payload	3 kg (6.6 lb)	5 kg	(11 lb)	7 kg (1	15.4 lb)	12 kg (2	26.4 lb)	18 kg (39.6 lb)	20 kg (4	14.1 lb)	
	Weight (including cables)	12 kg (26.46 lb)		23 kg (50.71 lb)		22 kg (48.50 lb)		41 kg (90.39 lb)		35 kg (77.16 lb)		68 kg (149.9 lb)		
Posis	Reach	626 mm	(24.64 in)	954 mm (37.5 in)		819 mm (32.2 in)		1327 mm (52.2 in)		1073 mm (42.24 in)		1780 mm (70.1 in)		
Basic Parameter	Repeatability	±0.02 mm (±0.00079 in)		±0.02 mm (±0.00079 in)		±0.02 mm (±0.00079 in)		±0.03 mm (±	±0.03 mm (±0.00118 in)		±0.03 mm (±0.00118 in)		±0.05 mm (±0.00120 in)	
	Degree of freedom	6		6			6	6	3	6		6		
	Programming	Graphical programming, and freedrive programming		Graphical programming, and freedrive programming		Graphical programming, and freedrive programming		Graphical programming, and freedrive programming		Graphical programming, and freedrive programming		Graphical programming, and freedrive programming		
	Demonstrator type	Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		
	Joint	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	
	Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	
	Joint 2	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	120°/s	-85°~+265°	120°/s	-85°~+265°	120°/s	
Movement	Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s	±175°	120°/s	
Wovement	Joint 4	-85°~+265°	220°/s	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	220°/s	
	Joint 5	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	220°/s	
	Joint 6	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	220°/s	
	Typical TCP speed	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1.5 m/s (4.921ft/s)	
	Typical consumption	150W		350W		350W		500)W	50	0W	750	DW	
	IP classification	IP54		IP54		IP54		IP54		IP54		IP	65	
Specifications		2 digital inputs		2 digital inputs		2 digital inputs		2 digita	l inputs	2 digital inputs		2 digital inputs		
Specifications	Tool I/O ports	Tool I/O ports 2 digital outputs 2 analog inputs		2 digital outputs		2 digital outputs		2 digital outputs		2 digital outputs		2 digital outputs		
				2 analog inputs		2 analog inputs		2 analog inputs		2 analog inputs		2 analog inputs		
	Footprint	129 mm	(5.079 in)	158 mm (6.220 in)		158 mm (6.220 in)		188 mm (7.402 in)		188 mm (7.402 in)		246 mm (9.685 in)		
	IP classification	IP	44	IF	44	IP44		IP44		IP	244	IP44		
	I/O ports	16 digital inputs, 16 digital out	outs, 2 analog inputs or outputs	s 16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		s 16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		
Control cabinet	Communication mode	TCP/IP, Modbus TCP, Modb	ous RTU, Profinet, Ethernet/IP	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		
Control cabillet	Power supply	100-240VA	C, 50-60Hz	100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		
	Size	410×307×235	(mm) (W×H×D)	410×307×235	(mm) (W×H×D)	410×307×235	(mm) (W×H×D)	410×307×235 (mm) (W×H×D)	410×307×235	(mm) (W×H×D)	410×307×235 (mm) (W×H×D)	
	Weight	13.5 kg (29.762 lb)	15.4 kg	(33.95 lb)	15.4 kg ((33.95 lb)	18 kg (3	9.68 lb)	18 kg (3	39.68 lb)	18 kg (3	9.68 lb)	

JAKA S Series Cobots Safety Protection IP65 rating Integrated force control JKS Hub quick app platform



Stay tuned for more new products

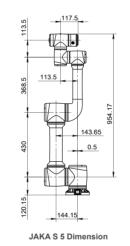


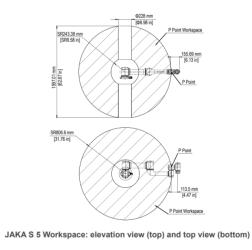


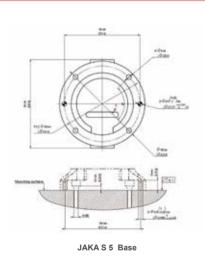
	Parameter	JAK	A S 5	JAKA	JAKA S 12		
	Payload	5 kg (11 lb)	12 kg (26.5 lb)			
Basic	Reach	954 mm	(37.6 in)	1327 mm (1327 mm (52.4 in)		
Parameter	Degrees of freedom	6	3	6			
	Typical consumption	350	Эw	500	w		
	Temperature		-10~50°	C(14~122°F)			
	Force/torque sensor	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z		
	Range	200N	24Nm	400N	48Nm		
Performance	Max affordable force	3000N	300Nm	3000N	300Nm		
	Overall accuracy	1% F.S.	1% F.S.	1% F.S.	1% F.S.		
	Distinguishability	0.1N	0.1Nm	0.1N	0.1Nm		
	Typical TCP speed	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1		
	Repeatability	±0.02 mm (±0.00079 in)	1	±0.03 mm (±0.00118 in)	1		
	Joint	Range of action	Joint speed	Range of action	Joint speed		
	Joint 1	±360°	180°/s	±360°	120°/s		
Movement	Joint 2	-85°~ +265°	180°/s	-85°~ +265°	120°/s		
	Joint 3	±175°	180°/s	±175°	120°/s		
	Joint 4	-85°~+265°	180°/s	-85°~+265°	180°/s		
	Joint 5	±360°	180°/s	±360°	180°/s		
	Joint 6	±360°	180°/s	±360°	180°/s		
	IP classification	IP 65		IP 65			
	Robot mounting	Any orie	entation	Any orientation			
	Footprint	158 mm (6.220 in)	188 mm (7	.402 in)		
Physical	Materials	Alumini	um, PC	Aluminiu	m, PC		
	Robot connection cable length	6 m (2	36 in)	6 m (23	36 in)		
	Weight	23 kg (50.7lb)	41 kg (9	0.4lb)		
	Humidity		10~	90% RH			

i: Overall accuracy: It represents the median typical value of the system error, including the measurement error of the sensor and the absolute positioning error of the robot, reflecting the overall accuracy of the robot system in measuring external forces applied to the robot's end under real operating conditions. ii:1% F.S.: 1% of the full scale.

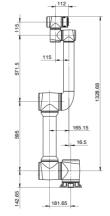
JAKA S 5 Drawings



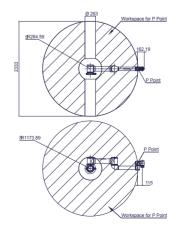




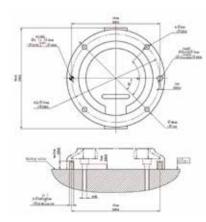
JAKA S 12 Drawings •







JAKA S 12 Workspace: elevation view (top) and top view (bottom)



JAKA S 12 Base





	Parameters	arameters JAK/		KA Ai 3 JAKA Ai 5		JAKA Ai 7		JAKA Ai 12		JAKA Ai 18	
	Payload	3 kg (6.6 lb)		5 kg (11 lb)		7 kg (15.4 lb)		12 kg (26.4 lb)		18 kg (39.6 lb)	
	Weight (including cables)	12 kg (2	26.46 lb)	23 kg	(50.71 lb)	22 kg (48.50 lb)		41 kg (90.39 lb)		35 kg (77.16 lb)	
	Reach	626 mm ((24.64 in)	954 mr	m (37.5 in)	819 mm (32.2 in)		1327 mm (52.2 in)		1073 mm (42.24 in)	
Basic Parameter	Repeatability	±0.02 mm (±0.00079 in)		±0.02 mm (±0.00079 in)		±0.02 mm (±0.00079 in)		±0.03 mm (±0.00118 in)		±0.03 mm (±0.00118 in)	
Farailletei	Degree of freedom	6			6		6		6	6	
	Programming	Graphical programming, and freedrive programming		Graphical programming,	and freedrive programming	Graphical programming, a	and freedrive programming	Graphical programming, and freedrive programming		Graphical programming, and freedrive programming	
	Demonstrator type	Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)		Mobile terminal (compo	uter/pad/mobile phone)	Mobile terminal (computer/pad/mobile phone)		Mobile terminal (computer/pad/mobile phone)	
	Joint	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed
	Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s
	Joint 2	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	120°/s	-85°,+265°	120°/s
Movement	Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s
Movement	Joint 4	-85°,+265°	220°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s	-85°,+265°	180°/s
	Joint 5	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Joint 6	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Typical TCP speed	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)
	Typical consumption	150W		350W		350W		500W		500W	
Specifications	IP classification	IP54		IP54		IP54		IP54		IP	P54
Opecifications	Tool I/O ports	2 digital input, 2 digital	2 digital input, 2 digital output, 2 analog output		2 digital input, 2 digital output, 2 analog output		output, 2 analog output	2 digital input, 2 digital output, 2 analog output		2 digital input, 2 digital	output, 2 analog output
	Footprint	129 mm (5.079 in)		158 mm (6.220 in)		158 mm (6.220 in)		188 mm (7.402 in)		188 mm (7.402 in)	
	Lens focal length	8 mm	16 mm	8 mm	16 mm	8 mm	16 mm	8 mm	16 mm	8 mm	16 mm
	Color mode	B&W/Color		B&W/Color		B&W/Color		B&W/Color		B&W/Color	
JAKA Lens 2D	Vision	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm	>70mm*50mm	>35mm*25mm
parameters	Precision	>0.08 mm	>0.04 mm	>0.08 mm	>0.04 mm	>0.08 mm	>0.04 mm	>0.08 mm	>0.04 mm	>0.08 mm	>0.04 mm
	Communications interface	Ethernet interface	(TCP/IP protocol)	Ethernet interfac	e (TCP/IP protocol)	Ethernet interface	e (TCP/IP protocol)	Ethernet interface	e (TCP/IP protocol)	Ethernet interface	e (TCP/IP protocol)
	Resolution	2592>	×1944	2592×1944		2592×1944		2592×1944		2592×1944	
	Frame rate	24F	FPS	24	1FPS	24FPS		24FPS 24F		4FPS	
	Input power		DC3	30-60V		DC30-60V					
	Input current		≤4	40A		≤40A					
	Size	180×28×47		mm (L×W×H)		180×28×47 mm (L×W×H)					
MiniCab cabinet	IP classification		IF	20				IF	220		
	I/O ports		7-way port; Input an	nd output configurable				7-way port; Input an	nd output configurable		
	Communication mode	1	TCP/IP, Modbus TCP, Modb	ous RTU, Profinet, Ethern	et/IP			TCP/IP, Modbus TCP, Modb	ous RTU, Profinet, Ethernet/IF	Р	
	Weight	, , ,		uding accessories)		About 1.7 kg (including accessories)					







	Parameters	JAKA Pro 5		JAKA Pro 12		JAKA Pro 16	
	Payload	5 kg (11 lb)		12 kg (26.4 lb)		16 kg (35.27 lb)	
	Weight (including cables)	23 kg (50.71 lb)		41 kg (90.39 lb)		79.7 kg (175.71lb)	
Basic	Reach	954 mm ((37.5 in)	1327 mm	(52.2 in)	1713 mm (67.44 lb)
Parameter	Repeatability	±0.02 mm (±	0.00079 in)	±0.03 mm (±	±0.00118 in)	±0.03 mm (±	0.00118 in)
	Degree of freedom	6		6	6	6	
	Programming	Graphical programming, ar	nd freedrive programming	Graphical programming, a	nd freedrive programming	Graphical programming, ar	nd freedrive programming
	Demonstrator type	Mobile terminal (comput	ter/pad/mobile phone)	Mobile terminal (compu	uter/pad/mobile phone)	Mobile terminal (comput	er/pad/mobile phone)
	Joint	Range of action	Joint speed	Range of action	Joint speed	Range of action	Joint speed
	Joint 1	±360°	180°/s	±360°	120°/s	±360°	120°/s
	Joint 2	-85°~+265°	180°/s	-85°~+265°	120°/s	-85°~+265°	120°/s
Movement	Joint 3	±175°	180°/s	±175°	120°/s	±175°	120°/s
oroc	Joint 4	-85°~+265°	180°/s	-85°~+265°	180°/s	-85°~+265°	180°/s
	Joint 5	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Joint 6	±360°	180°/s	±360°	180°/s	±360°	180°/s
	Typical TCP speed	1	1 m/s (3.281ft/s)	1	1 m/s (3.281ft/s)	1	1.5 m/s (4.921ft/s)
	Typical consumption	350W		500W		750	W
	IP classification	IP68		IP68		IP6	8
Specifications		2 Digital inputs		2 Digita	l inputs	2 Digital	inputs
opecifications	Tool I/O ports	2 Digital outputs		2 Digital	2 Digital outputs		outputs
		2 Analog	g input	2 Analog input		2 Analog input	
	Footprint	158 mm (l	6.220 in)	188 mm (7.402 in)		246 mm (9.685 in)	
	IP classification		14	IP44		IP44	
	I/O ports	16 digital inputs, 16 digital output	uts, 2 analog inputs or outputs	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs	
Control cabinet	Communication mode	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP	
Control Cabinet	Power supply	100-240VAC, 50-60Hz		100-240VAC, 50-60Hz		100-240VAC, 50-60Hz	
	Size	410×307×235 i	mm (W×H×D)	410×307×235	mm (W×H×D)	410×307×235 r	nm (W×H×D)
	Weight	15.4 kg (3	33.95 lb)	18 kg (3	9.68 lb)	18 kg (39	9.68 lb)

JAKA Lens 2D



Product description

The JAKA Lens 2D camera is equipped with a high-resolution industrial camera, a light source module, and an optional camera lens to provide our collaborative robots with machine vision capabilities. Despite its small and delicate appearance, this camera is highly effective. It can be installed either in a fixed position or at the end of the cobot.









Product Features **△**

Integrated design

The 2D camera consists of three key components: a camera, a lens, and a light source. It is able to communicate with a JAKA robot control cabinet through the web, making it an easy-to-use and highly effective addition to our cobots.

Easy operation

Our control cabinet is embedded with intelligent vision algorithms. Additionally, it features flexible communication interfaces that are able to adapt to the robot body, ensuring that it is a highly versatile and adaptable tool.

Scenario-adaptable

Our 2D camera also supports third-party camera extensions and custom external light sources, making it highly versatile and adaptable to a wide range of application scenarios.

Parameters	Lens 2D HR-CGC500-F08	Lens 2D HR-CGC500-F16		
Resolution	2592×1944	2592×1944		
Max frame rate	24 fps	24 fps		
Data interface	Gige	Gige		
Color mode	Black and white / color	Black and white / color		
Lens focal length	8 mm	16 mm		
Object distance	100 mm-1000 mm	100 mm-1000 mm		
Vision	>70×50 mm	>35×25 mm		
Pixel accuracy	>0.08mm	>0.04 mm		
System accuracy	≥ ±0.2 mm	≥ ±0.2 mm		
Image processing	Soft-trigger image acquisition, singl	e frame processing time within 1s		

JAKA Lens VPS

Product description

JAKA Lens VPS 2.0 is a cutting-edge technology that utilizes a high-performance AI-SoC chip, along with high-speed and large-capacity memory and storage. It is equipped with a high-performance acceleration engine, which can perform target detection, object recognition, human pose point extraction, and behavior understanding. The VPS is designed to be installed at the top of the cobot's working area, allowing the camera to monitor the behavior of inspected objects (both people and objects) in real time, ensuring the safety of both people and equipment. The camera also features a Gigabit Ethernet port, which supports data extraction and video visualization.





Product Features ≥



Built-in neural network accelerator for AI recognition and analysis of video



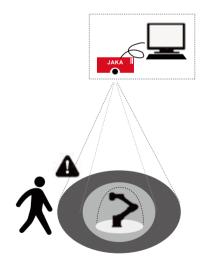
Event recording function, which can record key video segments, eliminate redundant information, trace back, and analyze more conveniently



Plug and play, no need to install software, access settings via browser



It can perform AI detection functions such as helmet wearing, personnel target tracking, personnel labor intensity, and video scoring calculation



Visual protection system working diagram

Basic parameters

Hardware platform	CMOS camera, embedded system, DSP, AI engine, etc.			
Dimensions	81×50×64mm			
Installation method	Directly above, sideways (suggested install at 45°)			
Communication interface	Ethernet interface, RS485, PNP optocoupler isolation DI and DO			

Visual parameters

Resolution	8.3 MP
Response time	≤100 ms
Installation height	≥3m (suggested)
Coverage surface	4 m x 2.1 m (adjustable)

JAKA MiniCobo

Product introduction

The JAKA MiniCobo is a small, rounded robot that is perfect for applications where appearance is important. Thanks to its built-in communication port, it doesn't require any external cables and can be easily connected to any tool that is compatible with JAKA. Additionally, JAKA's MiniCobo incorporates intelligent control algorithms, giving it a superior performance compared to its competitors. The MiniCobo operates quietly, making it an ideal solution for a range of industries including hospitality, education, retail, services, and entertainment, among others.



	kg		©	\odot
	Weigh	Payload	Reach	Repeatability
JAKA MiniCobo	9.4 kg	1 kg	580 mm	±0.1 mm
JAKA Mini 2	9.9 kg	2 kg	580 mm	±0.1 mm













	Parameter	JAKA MiniCobo	JAKA Mini 2			
	Payload	1 kg (2.21 lb)	2 kg (4.41 lb)			
	Weight (including cables)	9.4 kg (20.73 lb)	9.9 kg (21.83 lb)			
	Reach	580 mm (22.83 in)	580 mm (22.83 in)			
Product features	Repeatability	±0.1 mm (±0.003937 in)	±0.1 mm (±0.003937 in)			
	Degree of freedom	6	3			
	Programming	Graphical program	mming, free-drive			
	Demonstrator type	Mobile terminal (compu	uter/pad/mobile phone)			
	Collaborative operation	Collaborative operation	as ISO 10218-1: 2011			
	Joint	Range o	f action			
	Joint 1	±36	60°			
	Joint 2	±12	25°			
Working range	Joint 3	±13	30°			
and speed	Joint 4	±36	60°			
	Joint 5	±12	20°			
	Joint 6	±360°				
	Typical TCP speed	1 m/s (3	.8 ft/s)			
	Typical consumption	150W	180W			
	Rated voltage	24VDC	48VDC			
	Temperature range	0-50°C	0-50°C			
	IP classification	IP40	IP40			
	Installation	At any angle				
		2 Digital inputs				
Specifications	Tool I/O	2 Digital outputs				
		2 Analog input				
	Tool I/O power	24VDC				
	Tool I/O size	M8				
	Materials	Aluminum, PC				
	Footprint	124 mm (4.88 in)				
	Robot connection cable length	6 m (236 in)				
	Power input	20-60VDC				
	Current	≤40A				
	Size	180×128×47 mm (L×W×H)				
	IP classification	IP20				
MiniCab cabinet	I/O	7 Digital input: I/O configurable				
	I/O Power	24VDC				
	Installation	Panel/Guide Rail				
	Communication mode	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP				
	Weight	1.1 kg (2.43 lb)				
	Material	Alumminu	um, Steel			